



DATORKER® Strain Wave Gear System

New generation DATORKER® Strain Wave Gear System is the best solution for rotary applications. DATORKER® Strain Wave Gear System is suitable for wide range of applications like: semiconductor, precision laser cutting, 3C electronic automation, PCB industry, sustainable industry, automobile industry or any rotary related applications.

Feature /

High torque

Multiple reduction ratios available under the same size

High precision

Excellent positioning ability and repeatability

Compact size Lightweight

The best solution under space and weight constraints

Size

Tuning free

With high-performance
drive and built-in

software system

High rigidity
Equipped with
HIWIN crossed roller
bearings providing
high bending
moment

resistance



High torque	Maximum output torque > 300 Nm Volume and weight reduction by more than 50% compared to other types of reducers					
Compact structure						
High precision	Positioning accuracy < 60 arc-sec Repeatability < ± 6 arc-sec					
Easy installation	Can be installed in any direction / Can be programmed to any angle					
Total solution	Matching drives with absolute encoder / Built-in editable PDL program Support multiple control (I/O, Pulse, EtherCAT)					

Matching Drives /



• Variety of I / O functions

To support a number of different functions, you are free to configure the I/O pin functionality and adapt different hardware interface needs. This satisfies diverse requirements for different motion controllers with regards to their pin assignments and hardware interfaces.

• PDL (Process Description Language)

Easy-use process description language is provided. Complex motions can be designated via PDL, such as extrusion process, point-to-point motion, fixed speed control, homing process and so on. PDL gains the advantages of flexibility and programmability. For quick learning, a number of sample programs are provided in the PDL manual.



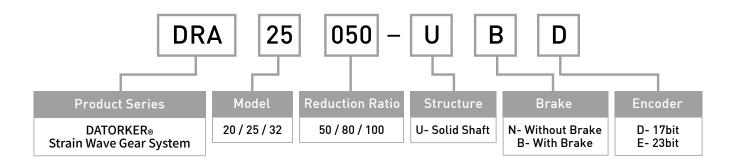
E1

D2T



• Built-in safe torque off function (STO) *available in E1 only
When STO is triggered, motor power will be cut off immediately providing safety function.

Product Specifications /

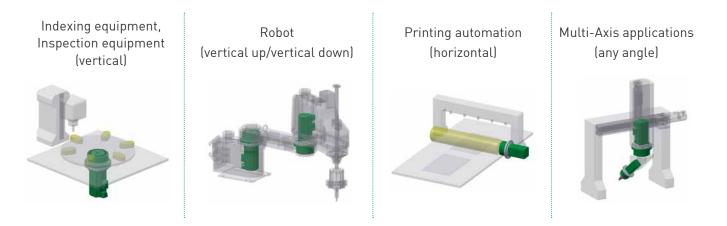


Specification Sheet /

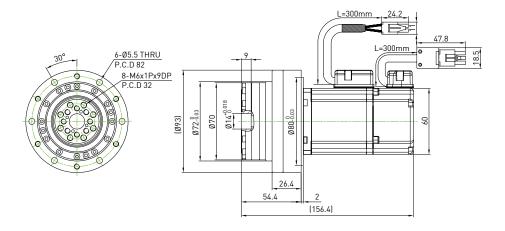
Model	Reduction Ratio	Power Supply: AC 220V					Encoder		Permissible Moment	Moment	Weight		Output	Positioning Accuracy	Repeatibility	
			Max Speed	Rated Speed		Rated Current	Control Mode	Encoder	Encoder Resolution	Load	Rigidity	Without Brake		Resolution	(uni- direction)	repeatibility
		Nm	rpm	rpm	Α	А		Type	(One Rotation of Output Shaft)	Nm	×10 ⁴ Nm/rad	kg	kg	pulse/rev	arc-sec	arc-sec
	50	56	90	60	5.1	1.7	Position	17bit Absolute	2 ¹⁷ (131,072)	91	12.8	2.4	3.0	6,553,600	<60	<±6
DRA20-D		74	56	37										10,485,760		
	100	82	45	30										13,107,200		
DRA25-D	50	98	90	60	7.8	2.6				156	24.2	3.3	3.9	6,553,600		
	80	137	56	37										10,485,760		
	100	157	45	30			CO							13,107,200		
DRA32-D	50	216	90	60	15.3	5.1	control (Pulse), EtherCAT(CoE)			313	53.9	6.8	7.5	6,553,600		
		304	56	37										10,485,760		
	100	333	45	30										13,107,200		
DRA20-E	50	56	120	60	6.4	1.6		23bit Absolute	2 ²³ [8,388,608]	91	12.8	2.3	2.6	419,430,400		
	80	74	75	37										671,088,640		
	100 50	82 98	60	30										838,860,800		
	80	137	112 70	60 37	10	2.5				156	24.2	3.3	3.9	419,430,400		
	100	157	56	30										671,088,640		
DRA32-E	50	216	96	60	18.6 4.0	4.65						6.9	7.6	838,860,800 419,430,400		
		304	60	37						313	53.9			671,088,640		
	100	333	48	30		4.03								838,860,800		

^{*}Standard parts include drive (preset as position control mode), motor cable (3M), encoder cable (3M)

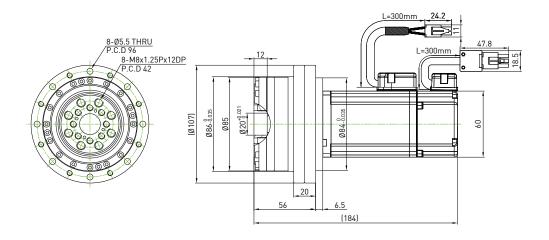
Product application and installation /



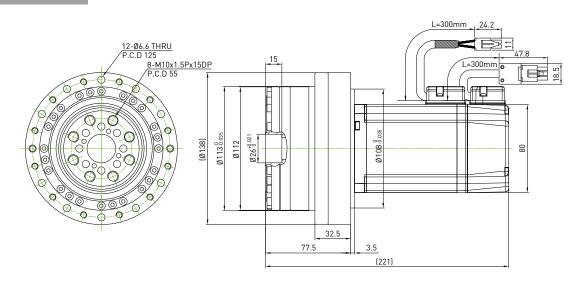
DRA20 UND



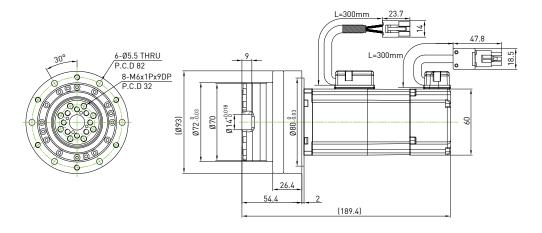
DRA25 UD -UND



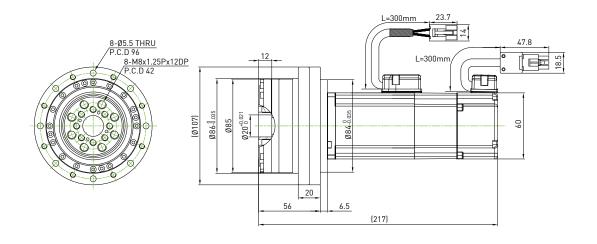
DRA32 UU -UND



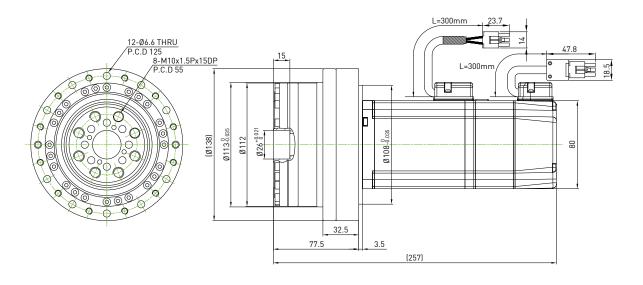
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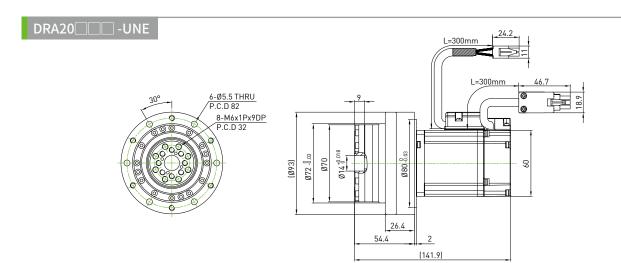


DRA25 UBD

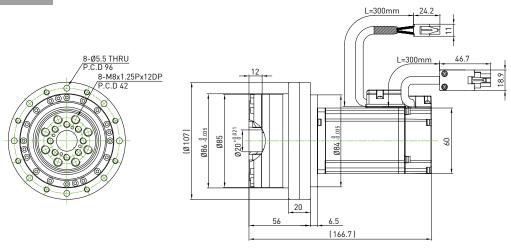


DRA32 UBD

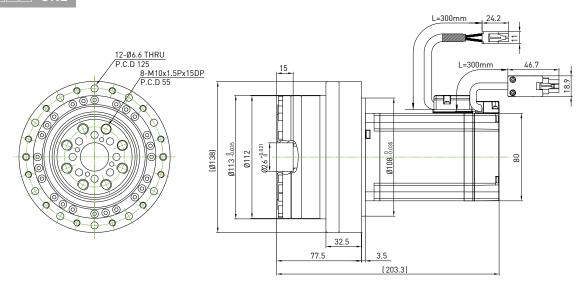




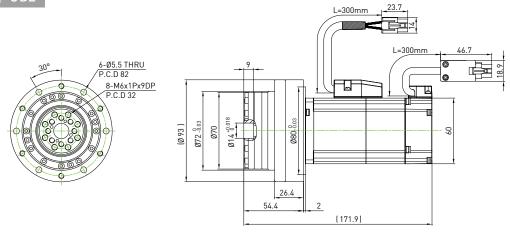
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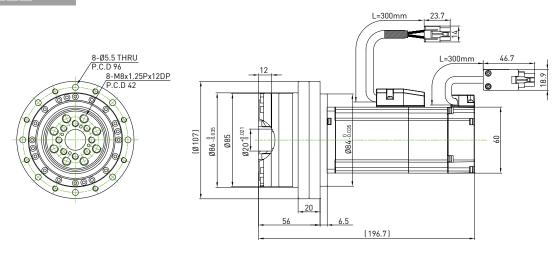
DRA32 U -UNE



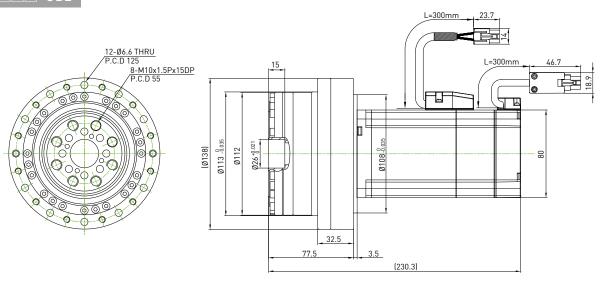
DRA20 UBE



DRA25 UBE



DRA32 UBE



HIWIN DATORKER® Strain Wave Gear System Inquiry Form

Customer name		Telephone							
Email		Date							
Applications	□Robot □Inspection equipment □Automation equipment □Electronics industry equipment □Machine tool □Medical equipment □Semiconductor □Others, please specify								
Selection	● Mechanism details Table diameter(D): (mm) Table weight (WD): (kg) Workpiece diameter(d): (kg) Workpiece weight(Wd): (kg) Distance between axis center and workpiece center (S): (mm)	• Operation par Maximum RPM Acceleration tin Deceleration tin Velocity time(tc							
Working environments	□Normal working environment (ambient temperature 0°C - 40°C, humidity under 80% RH) □Special working environment (ambient temperature :°C) □Harsh environment (dusty, wet, etc) □Other special environment :								
Installation type									
Brake	□No □Yes								
Drive	□D2T □E1(ST0)								
Input voltage	□220V Single phase □220V Three phase □0thers								
Power cable & Encoder cable	□3M (standard) □5M □7M □10M								
Optional accessories	□Control cable (including pulse + I/O pins) □USB transfer cable □Single phase filters								
Control type	☐Position control (pulse) ☐EtherCAT(CoE) □Othe	ers						
Host	□None □PLC/Brand: Model: □Axis card/Brand: Model:								
Other requirements	Other requirements								
Below to be filled in by HIWIN or Distributor Suggested Model & Specification:									



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